



THE UNIVERSITY OF
SYDNEY



Revisiting Classifier: Transferring Vision-Language Models for Video Recognition

Wenhao Wu^{1,2}

Zhun Sun²

Wanli Ouyang^{1,3}

¹The University of Sydney

²Baidu Inc.

³Shanghai AI Laboratory



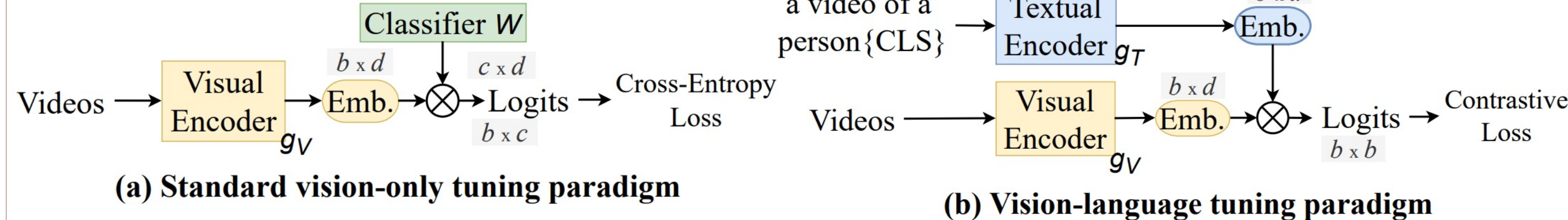
THE 37TH AAAI CONFERENCE ON
ARTIFICIAL INTELLIGENCE

FEBRUARY 7-14, 2023 • WASHINGTON, DC, USA
WALTER E. WASHINGTON CONVENTION CENTER

MOTIVATION

Existing transferring paradigm for video recognition

Efficient but not effective



Observation: the semantic information contained in the samples may correlate with inter-classes.

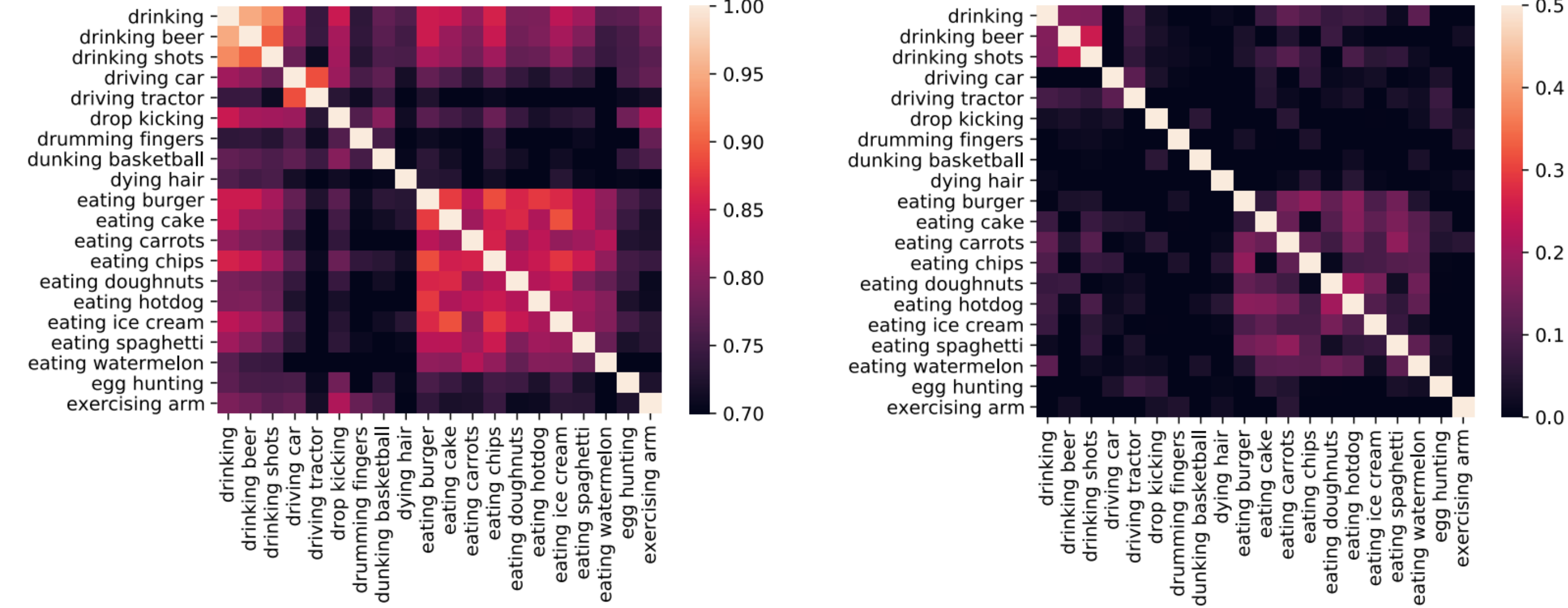


Figure. Inter-class correlation maps of “embeddings of class labels” for 20 categories on Kinetics-400. **Left:** The extracted textual vectors of class labels, **Right:** The “embeddings” from learned classifier.

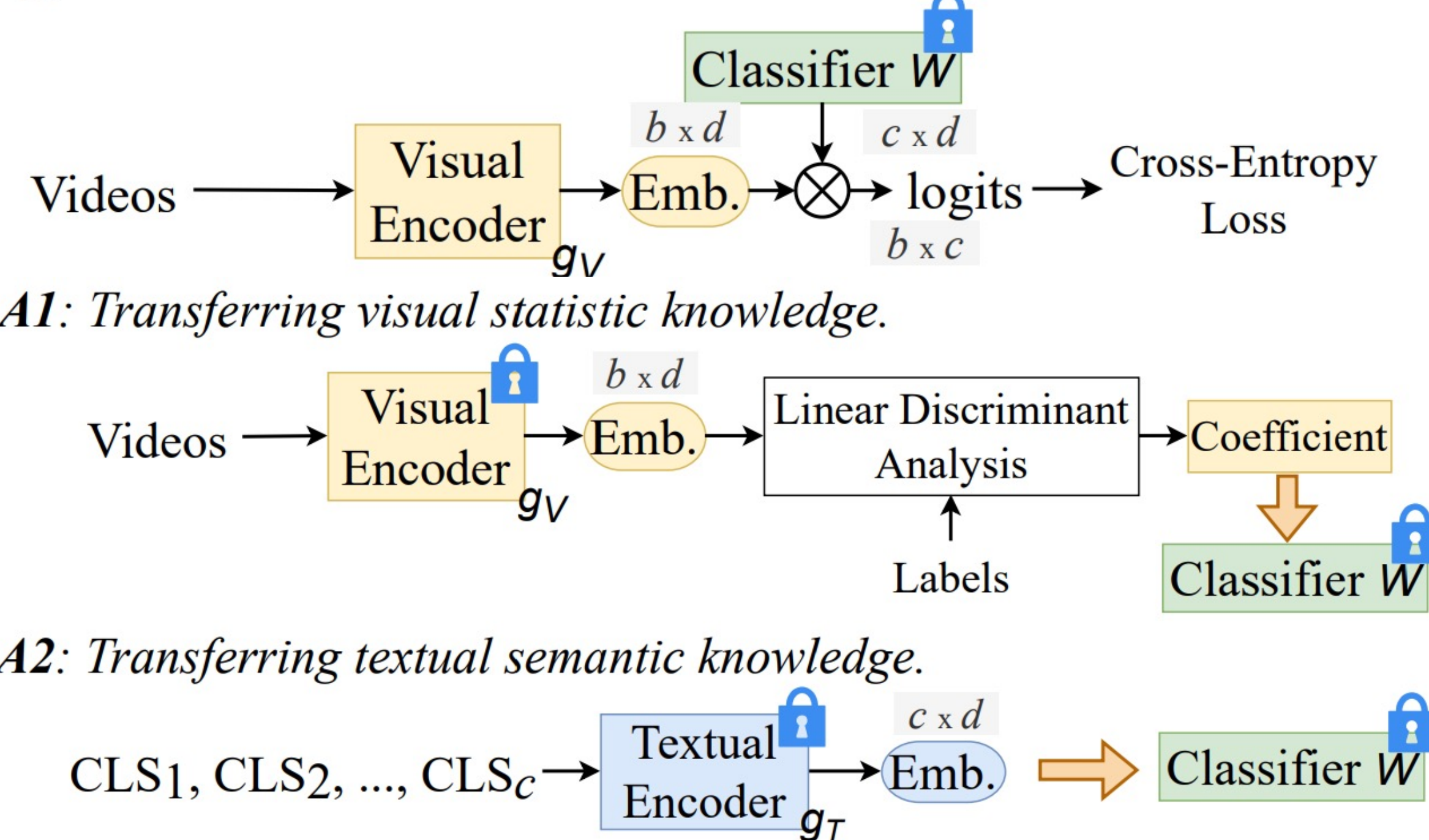
CONTRIBUTION

- We build a new recognition paradigm to improve the transferability using visual knowledge and textual knowledge from the well-pre-trained vision-language model.
- We conduct extensive experiments on popular video datasets (i.e., Kinetics-400 & 600, UCF-101, HMDB51 and ActivityNet) to demonstrate the transferability of our solution in many types of transfer learning, i.e., zero-shot / few-shot / general video recognition. Our approach democratizes the training on video datasets and achieves state-of-the-art performance on various video recognition settings, e.g., 87.8% top-1 accuracy on Kinetics-400, and outperforms previous methods by 20~50% absolute top-1 accuracy under zero-shot, few-shot settings.

METHOD

Revisiting Classifier: *From a frozen classifier perspective*

Q: How to obtain inter-class correlation?



(c) Revisiting the classifier for efficient tuning

ABLATION STUDIES

	Zero-shot	2-shot	Full-shot
<i>Vision-Only</i>	0.2	43.6	75.27
<i>Vision-Text</i>	54.2	66.4	80.13

Comparisons with vision-only framework

Paradigm	Batch Gather	Textual Encoder	Top-1	V100-days
Contrastive-Based	✓	online	81.2	6.7 (10*)
	✓	offline	80.7	6.6
	✗	online	77.8	3.5
	✗	offline	76.1	3.3
Ours	✗	offline	81.5	3.3

Comparisons with contrastive-based framework

Offline classifier from	Top 1
Random normal matrix	59.3
Random orthogonal matrix	59.4
Linear discriminant projection	80.8
DistilBERT	81.4
Textual encoder of CLIP	81.5

Method	Top-1	FLOPs	Params	Throughput
ViViT-L/16-320 [1]	81.3	3992G	310.8M	4.2 vid/s*
Ours ViT-B/32	78.5	23.7G	71.6M	322.5 vid/s
Ours ViT-B/16	81.5	90.3G	69.9M	126.5 vid/s
Ours ViT-L/14	85.4	415.4G	230.4M	35.5 vid/s

Exploration of different frozen classifiers

Analysis on inference efficiency

EXPERIMENTS

Comparisons with SOTAs

Method	Input	Pre-train	Top-1	Top-5	FLOPs×Views	Param
NL I3D-101 [58]	128×224 ²	IN-1K	77.7	93.3	359×10×3	61.8
MVFNet _{En} [60]	24×224 ²	IN-1K	79.1	93.8	188×10×3	-
SlowFast NL101 [14]	16×224 ²	Scratch	79.8	93.9	234×10×3	59.9
X3D-XXL [13]	16×440 ²	Scratch	80.4	94.6	144×10×3	20.3
MViT-B, 64×3 [11]	64×224 ²	Scratch	81.2	95.1	455×3×3	36.6
<i>Methods with large-scale pre-training</i>						
TimeFormer-L [2]	96×224 ²	IN-21K	80.7	94.7	2380×1×3	121.4
ViViT-L/16×2 [1]	32×320 ²	IN-21K	81.3	94.7	3992×4×3	310.8
VideoSwin-L [36]	32×384 ²	IN-21K	84.9	96.7	2107×10×5	200.0
ip-CSN-152 [51]	32×224 ²	IG-65M	82.5	95.3	109×10×3	32.8
ViViT-L/16×2 [1]	32×320 ²	JFT-300M	83.5	95.5	3992×4×3	310.8
ViViT-H/16×2 [1]	32×224 ²	JFT-300M	84.8	95.8	8316×4×3	647.5
TokLearner-L/10 [44]	32×224 ²	JFT-300M	85.4	96.3	4076×4×3	450
MTV-H [66]	32×224 ²	JFT-300M	85.8	96.6	3706×4×3	-
CoVeR [71]	16×448 ²	JFT-300M	86.3	-	-×1×3	-
Florence [69]	32×384 ²	FLD-900M	86.5	97.3	-×4×3	647
CoVeR [71]	16×448 ²	JFT-3B	87.2	-	-×1×3	-
VideoPrompt ViT-B/16 [25]	16×224 ²	WIT-400M	76.9	93.5	-	-
ActionCLIP ViT-B/16 [57]	32×224 ²	WIT-400M	83.8	96.2	563×10×3	141.7
Ours ViT-L/14	32×224 ²	WIT-400M	87.1	97.4	1662×4×3	230.7
Ours ViT-L/14	32×336 ²	WIT-400M	87.8	97.6	3829×1×3	230.7

Results on Kinetics-400 dataset

Comparison with Few-shot SOTAs

Method	shot	HMDB	UCF	ANet	K400
VideoSwin [36]	2	20.9	53.3	-	-
VideoPrompt [25]	5	56.6	79.5	-	58.5
X-Florence [40]	2	51.6	84.0	-	-
Ours ViT-L	0	53.8	71.9	75.6	61.0
	1	72.7	96.4	89.0	75.8
	2	73.5	96.6	90.3	78.2
	All	80.1	96.9	91.1	84.7

Comparison with Zero-shot SOTAs

Method	UCF* / UCF	HMDB* / HMDB	ANet* / ANet	Kinetics-600
GA [38]	17.3±1.1 / -	19.3±2.1 / -	-	-
TS-GCN [15]	34.2±3.1 / -	23.2±3.0 / -	-	-
E2E [3]	44.1 / 35.3	29.8 / 24.8	26.6 / 20.0	-
DASZL [27]	48.9±5.8 / -	- / -	-	-
ER [7]	51.8±2.9 / -	35.3±4.6 / -	-	42.1±1.4
ResT [32]	58.7±3.3 / 46.7	41.1±3.7 / 34.4	32.5 / 26.3	-
Ours	85.8±3.3 / 79.6	58.1±5.7 / 49.8	84.6±1.4 / 77.4	68.9±1.0

Method	Top-1	mAP
ListenToLook [16]	-	89.9
MARL [61]	85.7	90.1
DSANet [62]	-	90.5
TSQNet [63]	88.7	93.7
NSNet [64]	90.2	94.3

Ours ViT-L	92.9	96.5
Ours ViT-L (336↑)	93.3	96.9

Results on ActivityNet

Method	UCF-101	HMDB-51
ARTNet [55]	94.3%	70.9%
I3D [6]	95.6%	74.8%
R(2+1)D [52]	96.8%	74.5%
S3D-G [65]	96.8%	75.9%
TSM [33]	95.9%	73.5%
STM [24]	96.2%	72.2%
TEINet [35]	96.7%	72.1%
MVFNet [60]	96.6%	75.7%
TDN [56]	97.4%	76.4%

Ours ViT-L	98.1%	81.3%
Ours ViT-L (336↑)	98.2%	81.3%

Results on UCF101 & HMDB51